

GLOBAL ATTRACTIVITY OF A $(k + 1)^{TH}$ ORDER NONLINEAR DIFFERENCE EQUATION

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Abstract: In this paper, we investigate the local stability and global attractivity of the positive solutions of the $(k + 1)^{th}$ order nonlinear difference equation, $x_{n+1} = \frac{\alpha + \beta x_n}{\gamma - x_{n-k}}$ $n = 0, 1, 2, 3, \dots$ (1)

where $\alpha \geq 0, \gamma > \beta > 0$ are real numbers and $k \geq 1$ is an integer, and the initial conditions x_{-k}, \dots, x_{-1} and x_0 are arbitrary. The positive equilibrium of (1) is a global attractor with a basin that depends on certain conditions imposed on higher coefficients. The feasibility and efficiency of the proposed techniques are verified by numerical examples and simulation results through MATLAB.

Keywords: Attractivity, Equilibrium, Local stability, Non linear difference equation.

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Introduction: Consider (1), we prove that the positive equilibrium \bar{x} of (1) is a global attractor with a basin that depends on certain conditions of the coefficients. Let I be any interval of real numbers and F be a continuous function defined on I^{k+1} .

Then, for initial conditions $x_{-k}, \dots, x_{-1}, x_0 \in I$, consider the difference equation,

$$x_{n+1} = F(x_n, x_{n-1}, \dots, x_{n-k})$$

$$n = 0, 1, 2, 3, \dots \quad (2)$$

where $k \in \{1, 2, \dots\}$ is an integer, and the function $F(u_0, u_1, \dots, u_k)$ has continuous partial derivatives. Equation (2) has a unique solution $\{x_n\}$, where $n = -k$ to ∞ .

A point \bar{x} is called an equilibrium of (2) if $\bar{x} = F(\bar{x}, \bar{x}, \dots, \bar{x})$. That is, $x_n = \bar{x}$ for $n \geq 0$.

The linearized equation associated with (2) about an equilibrium \bar{x} is

$$y_{n+1} = \sum_{i=0}^k \frac{\partial F}{\partial u_i}(\bar{x}, \bar{x}, \dots, \bar{x}) y_{n-i}$$

$$n = 0, 1, 2, 3, \dots \quad (3)$$

And its characteristic equation is [5],[6],[8],[9],

$$\lambda^{k+1} = \sum_{i=0}^k \frac{\partial F}{\partial u_i}(\bar{x}, \bar{x}, \dots, \bar{x}) \lambda^{k-i} \quad (4)$$

This paper is organized as follows: Section 2 describes the preliminaries. Local stability and Global attractivity of (1) are shown in Section 3. Section 4 provides the numerical examples and simulation results. Section 5 concludes the paper.

Preliminaries:

Definition 2.1:

1) The equilibrium point \bar{x} of (2) is called locally stable if for every $\epsilon > 0$, there exists $\delta > 0$ such that for all $x_{-k}, \dots, x_{-1}, x_0 \in I$ with $\sum_{i=-k}^0 |x_i - \bar{x}| < \delta$, we have $|x_n - \bar{x}| < \epsilon$ for all $n \geq -k$.

2) The equilibrium point \bar{x} of (2) is called a global attractor if $x_{-k}, x_{-(k-1)}, \dots, x_0 \in I$ always implies $\lim_{n \rightarrow \infty} x_n = \bar{x}$.

3) The equilibrium point \bar{x} of (2) is called unstable if it is not locally stable.

Theorem 2.2: Assume that F is a C^1 function and let \bar{x} be an equilibrium point of (2). Then the following statements are true:

i) If all the roots of the polynomial equation

$$\lambda^{k+1} - \sum_{i=0}^k \frac{\partial F}{\partial u_i}(\bar{x}, \bar{x}, \dots, \bar{x}) \lambda^{k-i} = 0 \quad (5)$$

lie in an open unit disk $|\lambda| < 1$, then the equilibrium \bar{x} of (2) is asymptotically stable.

ii) If atleast one root of (5) has an absolute value greater than one, then the equilibrium \bar{x} of (2) is unstable [5],[6],[8],[9].

3. Local Stability and Global Attractivity:

Lemma 3.1

Assume that $p, q \in \mathbb{R}$ and $k \in \{0, 1, \dots\}$. Then

$$|p| + |q| < 1 \quad (6)$$

is a sufficient condition for the asymptotic stability of the difference equation, $x_{n+1} + px_n + qx_{n-k} = 0$.

$$n = 0, 1, 2, 3, \dots \quad (7)$$

Now, let us consider the rational recursive sequence,

$$x_{n+1} = \frac{\alpha + \beta x_n}{\gamma - x_{n-k}}$$

$$n = 0, 1, 2, 3, \dots \quad (8)$$

Where

$$\alpha > 0, \gamma > \beta > 0, k \in \{1, 2, 3, \dots\}. \quad (9)$$

If (9) holds and

$$\alpha < (\gamma - \beta)^2 / 4 \quad (10)$$

then (1) has two positive equilibria,

$$\bar{x}_1 = \frac{(\gamma - \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2} \quad (11)$$

$$\bar{x}_2 = \frac{(\gamma - \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2} \quad (12)$$

The linearized equation of (8) about the equilibrium \bar{x}_i is

$$y_{n+1} - \frac{\beta}{\gamma - \bar{x}_i} y_n - \frac{\bar{x}_i}{\gamma - \bar{x}_i} y_{n-k} = 0$$

$$i = 0, 1, 2, \dots, n = 0, 1, 2, 3, \dots \quad (13)$$

The characteristic equation associated with (13) about \bar{x}_1 is

$$\lambda^{k+1} - \frac{2\beta}{(\gamma + \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}} \lambda^k - \frac{(\gamma - \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{(\gamma + \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}} = 0 \quad (14)$$

In the view of

$$\left| \frac{(\gamma - \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{(\gamma + \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}} \right| > 1 \quad (15)$$

the equilibrium point \bar{x}_1 of (8) is unstable.

For the positive equilibrium \bar{x}_2 , in the view of condition (9), we have

$$\bar{x}_2 = \frac{(\gamma - \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2} < \frac{(\gamma - \beta)}{2} < \gamma \quad (16)$$

Consider,

$$\begin{aligned} |p| + |q| &= \frac{\beta}{\gamma - \bar{x}_2} + \frac{\bar{x}_2}{\gamma - \bar{x}_2} = \frac{\beta + \bar{x}_2}{\gamma - \bar{x}_2} \\ &= \frac{\beta + \frac{(\gamma - \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2}}{\gamma - \frac{(\gamma - \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2}} \\ &= \frac{(\gamma + \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{(\gamma + \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}} < 1 \end{aligned} \quad (17)$$

which by Lemma 3.1, implies that \bar{x}_2 is locally asymptotically stable [7],[8].

Now we show that the positive equilibrium \bar{x} of (1) is a global attractor with a basin that depends on certain conditions imposed on the coefficients.

We consider the case $\alpha > 0$.

Theorem 3.2

Consider the difference equation,

$$\begin{aligned} x_{n+1} &= g(x_n, x_{n-k}) \\ n &= 0, 1, 2, \dots \end{aligned} \quad (18)$$

where $k \in \{1, 2, \dots\}$, $g \in C[(0, \infty), (0, \infty)]$ is increasing in each of its arguments and the initial conditions $x_{-k}, \dots, x_{-1}, x_0$ are positive. Assume that (18) has a unique positive equilibrium \bar{x} and that the function h is defined by,

$$h(x) = g(x, x), \quad x \in (0, \infty) \quad (19)$$

satisfies

$$(h(x) - x)(x - \bar{x}) < 0$$

$$\text{for } x \neq \bar{x} \quad (20)$$

Then \bar{x} is a global attractor of all the positive solutions of (18).

Lemma 3.3

Assume that (9) and (10) holds. Then the following statements are true:

- (i) $F(x, x)$ is a strictly increasing function in $(-\infty, \gamma)$.
- (ii) If $(u_0, u_k) \in [-\alpha/\beta, \gamma) \times (-\infty, \gamma)$. Then F is a strictly increasing function in each of its arguments.

Lemma 3.4: Assume that (9) and (10) holds.

1) $0 < \bar{x}_2 < \bar{x}_1 < \gamma$ (21)

2) Suppose that the function h is defined by

$$h(x) = F(x, x), \quad x \in (0, \bar{x}_1) \quad (22)$$

Then $(h(x) - x)(x - \bar{x}_2) < 0$ for $x \neq \bar{x}_2$.

Proof : 1) Since $\bar{x}_1 - \gamma = \frac{(\gamma - \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2} - \gamma$
 $= \frac{-\gamma - \beta + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2} < 0$

Therefore, we have $\bar{x}_1 < \gamma$

By the definitions of \bar{x}_1 and \bar{x}_2 , we have

$$0 < \bar{x}_2 < \bar{x}_1 < \gamma.$$

The proof is complete.

2) By the definition of h , we have

$$\begin{aligned} (h(x) - x)(x - \bar{x}_2) &= \left(\frac{\alpha + \beta x}{\gamma - x} - x\right)(x - \bar{x}_2) \\ &= \left(\frac{\alpha + \beta x - \gamma x + x^2}{\gamma - x}\right)(x - \bar{x}_2) \\ &= \left(\frac{x^2 - (\gamma - \beta)x + \alpha}{\gamma - x}\right)(x - \bar{x}_2) \end{aligned}$$

$$= \frac{1}{\gamma - x} \left(x - \frac{(\gamma - \beta) + \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2}\right)$$

$$\begin{aligned} &\times \left(x - \frac{(\gamma - \beta) - \sqrt{(\gamma - \beta)^2 - 4\alpha}}{2}\right)(x - \bar{x}_2) \\ &= \frac{1}{\gamma - x} (x - \bar{x}_1)(x - \bar{x}_2)^2 < 0 \text{ for } x \neq \bar{x}_2. \end{aligned}$$

The proof is complete.

Theorem 3.5: Assume that (9) and (10) holds. Let $\{x_n\}$ be any solution of (1). If

$(x_{-k}, \dots, x_{-1}, x_0) \in (-\infty, \bar{x}_1]^k \times [-\alpha/\beta, \bar{x}_1]$, then $0 \leq x_n \leq \bar{x}_1$, for $n \geq 1$.

Proof: By part (2) of Lemma 3.4, we have

$$\begin{aligned} 0 &= F(-\alpha/\beta, x_{-k}) \leq x_1 \\ &= F(x_0, x_{-k}) \leq F(\bar{x}_1, \bar{x}_1) = \bar{x}_1, \end{aligned} \quad (23) \text{ and}$$

$$\begin{aligned} 0 &< F(0, x_{-k+1}) \leq x_2 \\ &= F(x_1, x_{-k+1}) \leq F(\bar{x}_1, \bar{x}_1) = \bar{x}_1. \end{aligned} \quad (24)$$

Hence, the result follows by induction. Therefore the proof is complete.

Theorem 3.6: Assume that (9) and (10) holds. Then the positive equilibrium \bar{x}_2 of (1) is a global attractor with a basin $S = (0, \bar{x}_1)^{k+1}$.

Proof: Let $\{x_n\}$ be a solution of (1) with the initial conditions $(x_{-k}, \dots, x_{-1}, x_0) \in S$. Then, by part (2) of Lemma 3.4 and Theorem 3.5, the function $F(u_0, u_k) \in C[(0, \bar{x}_1), (0, \bar{x}_1)]$ is a strictly increasing function in each of its arguments and the initial conditions $x_{-k}, \dots, x_{-1}, x_0$ are positive. Let the function h be defined by

$$h(x) = F(x, x), \quad x \in (0, \bar{x}_1) \quad (25)$$

Then by part (2) of Lemma 3.4, we have $(h(x) - x)(x - \bar{x}_2)$

$$= \frac{1}{\gamma - x} (x - \bar{x}_1)(x - \bar{x}_2)^2 < 0, \quad x \neq \bar{x}_2 \quad (26)$$

By Theorem 3.2, \bar{x}_2 is a global attractor of all the positive solutions of (1). Then,

$$\lim_{n \rightarrow \infty} x_n = \bar{x}_2 \quad (27)$$

The proof is complete.

Theorem 3.7: Assume that (9) and (10) holds. Then the positive equilibrium \bar{x}_2 of (1) is a global attractor with a basin $S = (-\infty, \bar{x}_1]^k \times [-\alpha/\beta, \bar{x}_1] \setminus \{(\bar{x}_1, \dots, \bar{x}_1)\}$.

Proof: Let $\{x_n\}$ be a solution of (1) with initial conditions $(x_{-k}, \dots, x_{-1}, x_0) \in S$. Then by Theorem 3.5, we have $x_n \in (0, \bar{x}_1)$, for $n \geq 2$.

Hence, Theorem 3.6 implies that $\lim_{n \rightarrow \infty} x_n = \bar{x}_2$

The proof is complete.

Now, we consider the case $\alpha = 0$.

We find the asymptotic stability of the difference equation,

$$x_{n+1} = \frac{\alpha + \beta x_n}{\gamma - x_{n-k}}, \quad n = 0, 1, \dots, \quad (28)$$

where $\beta, \gamma > 0$, and $k \geq 1$.

By putting $x_n = \beta y_n$, (28) yields $y_{n+1} = \frac{y_n}{A - y_{n-k}}$, $n = 0, 1, \dots$, (29)

where $A = \gamma/\beta$. Equation (29) has two equilibrium points $\bar{y}_1 = 0$ and $\bar{y}_2 = A - 1$.

The linearized equation associated with (29) about \bar{y}_i

$$\begin{aligned} z_{n+1} - \frac{1}{A - \bar{y}_i} z_n - \frac{\bar{y}_i}{A - \bar{y}_i} z_{n-k} &= 0 \\ i=1, 2 \text{ and } n &= 0, 1, 2, \dots \end{aligned} \quad (30)$$

The characteristic equation of (30) about \bar{y}_1 is

$$\lambda^{k+1} - \frac{1}{A} \lambda^k = 0 \quad (31)$$

This equation has two roots.

$$\lambda_1=0 \text{ and } \lambda_2=\frac{1}{A} \quad (32)$$

Hence, by theorem 2.2

- (1) if $\gamma > \beta$ then \bar{y}_1 is asymptotically stable.
 - (2) if $\gamma < \beta$ then \bar{y}_1 is a saddle point and
 - (3) if $\gamma = \beta$ then linearized stability analysis fails.
- we assume that $\gamma > \beta$ which implies, $A > 1$.

Lemma 3.8: Assume that the initial conditions $(y_{-k}, \dots, y_{-1}, y_0) \in [0, \bar{y}_2]^{k+1} \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}$. Then every solution $\{y_n\}$ of (29) is nonnegative and monotonically decreases to zero.

Proof: Since,

$(y_{-k}, \dots, y_{-1}, y_0) \in [0, \bar{y}_2]^{k+1} \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}$, we have

$$0 \leq y_1 = \frac{y_0}{A-y_{-k}} \leq \frac{\bar{y}_2}{A-\bar{y}_2} = \bar{y}_2 \quad (33)$$

and

$$0 \leq y_2 = \frac{y_1}{A-y_{1-k}} \leq \frac{\bar{y}_2}{A-\bar{y}_2} = \bar{y}_2. \quad (34)$$

By induction, we can see that $0 \leq y_n \leq \bar{y}_2$, for $n \geq -k$.

Since, for $n \geq 0$,

$$\begin{aligned} y_n - y_{n+1} &= y_n - \frac{y_n}{A-y_{n-k}} \\ &= \frac{y_n}{A-y_{n-k}} (A-1-y_{n-k}) \geq 0 \end{aligned} \quad (35)$$

Then, $y_n \geq y_{n+1}$ for $n \geq 0$.

Hence, $\{y_n\}$ is a non negative and monotonically decreasing sequence.

Set $\lim_{n \rightarrow \infty} y_n = l > 0$

By taking limits on both sides of (29), we have $l = \frac{l}{A-l}$

Then, $l = 0$ or $l = A - 1$.

If $l = A - 1 = \bar{y}_2$, then by the monotonic character of sequence $\{y_n\}$, we have $y_n = \bar{y}_2$, for all $n \geq 0$. Hence $y_{-k} = \dots = y_{-1} = \bar{y}_2$. This is a contradiction. So, $l = 0$. The proof is complete.

Corollary 3.9: The equilibrium $\bar{y}_1 = 0$ of (29) is a global attractor with a basin

$$S = [0, \bar{y}_2]^{k+1} \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}.$$

Theorem 3.10: The equilibrium $\bar{y}_1 = 0$ of (29) is a global attractor with a basin

$$S = (-\infty, \bar{y}_2]^k \times [0, \bar{y}_2] \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}.$$

Proof: Assume $(y_{-k}, \dots, y_{-1}, y_0) \in S$, then we have

$$\begin{aligned} 0 &= \frac{0}{A-y_{-k}} \leq y_1 = \frac{y_0}{A-y_{-k}} \\ &< \frac{\bar{y}_2}{A-\bar{y}_2} = \bar{y}_2 \end{aligned}$$

$$0 \leq y_2 = \frac{y_1}{A-y_{1-k}} < \frac{\bar{y}_2}{A-\bar{y}_2} = \bar{y}_2$$

The result now follows from Corollary 3.9 and the proof is complete[7],[8].

Simulation Results: To enrich our results of this section, we consider the following numerical examples which represents different types of solutions to (1).

Example 4.1: Consider, $x_{-5} = 1, x_{-4} = 2, x_{-3} = 4, x_{-2} = -1, x_{-1} = -2, x_0 = 7, \alpha = 1, \beta = -2$, and $\gamma = 4$

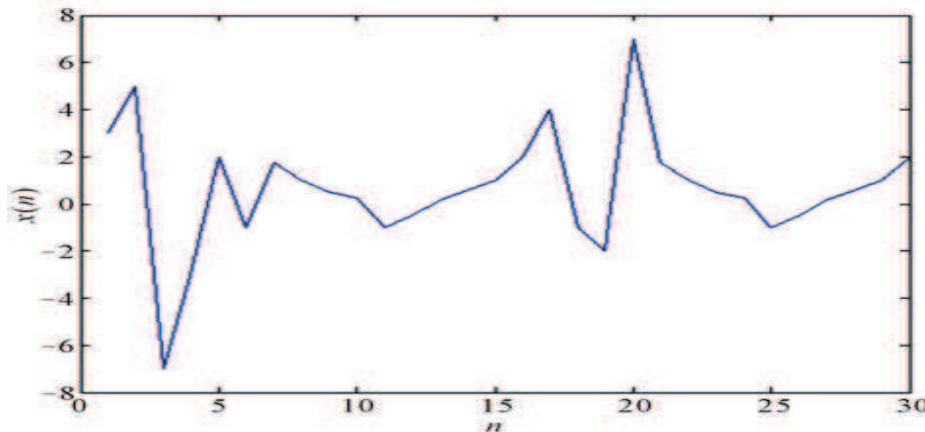


Fig 1: Plot of Example 4.1 of (1)

Example 4.2: Consider $x_{-5} = 1, x_{-4} = -1, x_{-3} = 2, x_{-2} = -6, x_{-1} = 5, x_0 = -4, \alpha = 3, \beta = 1$, and $\gamma = -1$

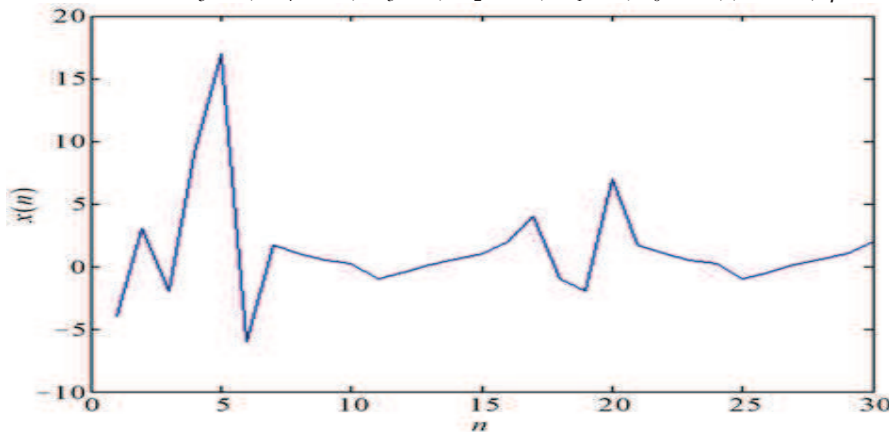


Fig 2: Plot of Example 4.2 of (1)

Conclusion: In this paper ,we have investigated the local stability and global attractivity of a nonlinear (K+1)th order difference equation,

$$x_{n+1} = \frac{\alpha + \beta x_n}{\gamma - x_n - k} \quad n=0,1,2,3\dots$$

We arrived the following as a certain key features:

1. The equilibrium point \bar{x}_1 of (1) is unstable whereas \bar{x}_2 is locally asymptotically stable.

2. The positive equilibrium \bar{x}_2 of (1) is a global attractor with the basins
 - i. $S = (0, \bar{x}_1)^{k+1}$ and
 - ii. $S = (-\infty, \bar{x}_1]^k \times [-\alpha/\beta, \bar{x}_1]$
3. The equilibrium $\bar{y}_1 = 0$ of (29) is a global attractor with the basins $S = [0, \bar{y}_2]^{k+1} \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}$ and $S = (-\infty, \bar{y}_2]^k \times [0, \bar{y}_2] \setminus \{(\bar{y}_2, \dots, \bar{y}_2)\}$.

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