

TOTAL WEIGHT DOMINATING VERTEX SET ON S - VALUED GRAPHS

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Abstract: In [1] and [3] the authors studied the notion of domination in Graphs. In [6] we have studied the notion of S- valued graphs, where S is a semiring. In [5], we have studied the notion of vertex domination in S-valued Graphs. In this paper, we introduce the notion of Total weight dominating vertex set on S- valued graphs and prove simple properties.

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Introduction: In [1], Berge introduced the notion of domination in graphs. In [3], Haynes and others continued the study of the notion of domination in Graphs. In [2], the authors studied the notion of total domination in Graphs. Motivated by the concept of S-valued graphs in [4] by Golan, in [6] we have studied the notion of S- valued graphs in detail, where S is a semiring. In [5], we have studied the notion of vertex domination in S-valued Graphs. In this paper, we introduce the notion of Total weight dominating vertex set on S-valued graphs and prove simple properties.

Preliminaries: In this section, we recall some basic definitions that are needed for our work.

Definition 2.1: [4] A semiring $(S, +, \cdot)$ is an algebraic system with a non-empty set S together with two binary operations + and \cdot such that

1. $(S, +, o)$ is a monoid.
2. (S, \cdot) is a semigroup.
3. for all $a, b, c \in S$, $a \cdot (b+c) = a \cdot b + a \cdot c$ and $(a + b) \cdot c = a \cdot c + b \cdot c$.
4. $o \cdot x = x \cdot o = o, \forall x \in S$.

Definition 2.2: Let $(S, +, \cdot)$ be a semiring. A canonical Pre-order \preceq in S is defined as follows: for $a, b \in S$, $a \preceq b$ if and only if, there exist $a - c \in S$ such that $a + c = b$.

Definition 2.3: [6] Let $G = (V, E)$ be a given graph with $V, E \neq \emptyset$. For any semiring $(S, +, \cdot)$ a semiring-valued graph (or a S - valued graph), G^S , is defined to be the graph $G^S = (V, E, \sigma, \psi)$ where $\sigma : V \rightarrow S$ and $\psi : E \rightarrow S$ is defined to be $\psi(x, y) = \begin{cases} \min\{\sigma(x), \sigma(y)\} & \text{if } \sigma(x) \preceq \sigma(y) \text{ or } \sigma(y) \preceq \sigma(x) \\ 0 & \text{otherwise} \end{cases}$ for every unordered pair (x, y) of $E \subset V \times V$. We call σ , a S- vertex set and ψ , a S edge set of G^S .

Definition 2.6: [5] A vertex v in G^S is said to be a weight dominating vertex if $\sigma(u) \preceq \sigma(v), \forall u \in V$.

Definition 2.6: [5] A subset $D \subseteq V$ is said to be a weight dominating vertex set of G^S if for each $v \in D$, $\sigma(u) \preceq \sigma(v), \forall u \in N_S(v)$.

Definition 2.7: [5] If D is a weight dominating vertex set of G^S , then the scalar cardinality of D, denoted by $|D|_S$, is defined by $|D|_S = \sum_{v \in D} \sigma(v)$.

Definition 2.8: [5] The cardinality of the minimal weight dominating vertex set $D \subseteq V$ is called the weight dominating vertex number of G^S . It is denoted by $\gamma_V^S(G^S)$. That is ,

$$\gamma_V^S(G^S) = (|D|_S, |D|)$$
.

Total Weight Dominating Vertex Set on S-Valued Graphs: In this section, we introduce the notion of total weight dominating vertex set on S-valued Graphs and obtain some simple results. First we fix a notation.

Notation: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. Denote $V_S = \{(\sigma(v_i), v_i) / i = 1, 2, 3, \dots, n \text{ and } \sigma(v_i) \in S\}$.

Definition 3.1: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. Let $T_D^S \subseteq V$. The open neighbourhood of T_D^S , denoted by $N_S(T_D^S)$, is defined by $N_S(T_D^S) = \cup_{v \in T_D^S} N_S(v)$.

Definition 3.2: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. Let $T_D^S \subseteq V$. The closed neighbourhood of T_D^S , denoted by $N_S[T_D^S]$, is defined by $N_S[T_D^S] = \cup_{v \in T_D^S} N_S[v]$.

Definition 3.3: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. Let $T_D^S \subseteq V$. For any $v \in T_D^S$ The private neighbour set of v with respect to T_D^S , denoted by $PN_S[v, T_D^S]$, is defined by $PN_S[v, T_D^S] = N_S[v] - N_S[T_D^S - \{v\}]$.

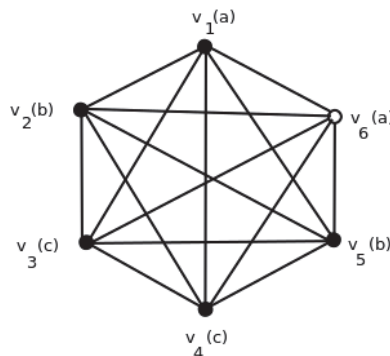
Definition 3.4: If $N_S(T_D^S) = V_S$, then T_D^S is called a total weight dominating vertex set of G^S .

Example 3.5: Let $(S = \{o, a, b, c\}, +, \cdot)$ be a semiring with the following cayley tables :

| | | | | |
|---|---|---|---|---|
| + | o | a | b | c |
| o | o | a | b | c |
| a | a | a | a | a |
| b | b | a | b | b |
| c | c | a | b | c |

| | | | | |
|---|---|---|---|---|
| · | o | a | b | c |
| o | o | o | o | o |
| a | o | a | a | a |
| b | o | b | b | b |
| c | o | b | b | b |

Let \preceq be a canonical pre-order in S, given by
 $o \preceq o, o \preceq a, o \preceq b, o \preceq c, a \preceq a, b \preceq b, b \preceq a, c \preceq c, c \preceq a, c \preceq b$.
 Consider the S-valued graph G^S :



Consider $T_D^S = \{v_1(a), v_2(b), v_3(c), v_4(c), v_5(b)\}$
 Hence $N_S[T_D^S] = \{v_1(a), v_2(b), v_3(c), v_4(c), v_5(b), v_6(a)\}$
 $= V_S$
 $\therefore T_D^S = \{v_1(a), v_2(b), v_3(c), v_4(c), v_5(b)\}$ is a total weight dominating vertex set of the given G^S .

Definition 3.6: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. Let $T_D^S \subseteq V$ is said to be a minimal total weight dominating vertex set if T_D^S is a total weight dominating vertex set and no proper subset of T_D^S is a total weight dominating vertex set.

Example 3.7: From the above example $T_D^S = \{v_1(a), v_2(b), v_3(c), v_4(c), v_5(b)\}$ and $T_D^S = \{v_2(b), v_3(c), v_4(c), v_5(b), v_6(a)\}$ and $T_D^S = \{v_1(a), v_2(b), v_3(c), v_5(b), v_6(a)\}$ are total weight dominating vertex sets of given G^S .

Definition 3.8: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. The cardinality of the minimal weight dominating vertex set is called the total weight dominating vertex number of G^S . That is, $\gamma_{T_D^S}^S(G^S) = (|T_D^S|_S, |T_D^S|)$ where T_D^S is a minimal total weight dominating vertex set of G^S .

Remark: Minimal weight dominating vertex set in a S-valued graph need not be, in general, unique.

Definition 3.9: If $G^S = (V, E, \sigma, \psi)$ is a S-valued graph. Let $T_D^S \subseteq V$ is said to be a independent total weight dominating vertex set if

- i) T_D^S is a total weight dominating vertex set.
- ii) No two vertices of T_D^S are adjacent in a total weight dominating vertex set.

And is denoted $\alpha_{T_D^S}^S(G^S)$, is defined as

$\alpha_{T_D^S}^S(G^S) = (|T_D^S|_S, |T_D^S|)$, where T_D^S is a minimal independent total weight dominating vertex set.

Remark: By the definition of the total weight dominating vertex set and the above remark we observe that an minimal independent weight dominating vertex set is also a total weight dominating vertex set of G^S .

Definition 3.10: An upper total weight dominating vertex number of $G^S = (V, E, \sigma, \psi)$, denoted by $\Gamma_{T_D^S}^S(G^S) = \max\{|T_D^S|_S, |T_D^S|\}$, where T_D^S is a minimal total weight dominating vertex set of G^S .

Theorem 3.11: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. A star on n vertices, where $n \geq 1$ then $\gamma_{T_D^S}^S(G^S) = (\sigma(v), 1)$, where v is the pole of the star graph G^S .

Proof: Let G^S be a star. Then the pole $\{v_1, \sigma(v_1)\}$ with maximum σ value in S dominates all other vertices showing that $T_D^S = \{v_1, \sigma(v_1)\}$.

Hence $N_S(T_D^S) \subseteq (V-D)_S$ and $N_S[T_D^S] = V_S$.

Therefore $\{v_1, \sigma(v_1)\}$ is a total weight dominating vertex set in G^S .

$\gamma_{T_D^S}^S(G^S) = (\sigma(v), 1)$, where v is the pole of the star graph G^S .

Theorem 3.12: Consider the S-valued graph $G^S = (V, E, \sigma, \psi)$. For any cycle on n vertices, where $n \geq 1$ the total weight dominating vertex number $\gamma_{T_D^S}^S(G^S) = \begin{cases} (\sum \sigma(v_i), \frac{n}{2}) \text{ where } n \text{ is even.} \\ (\sum \sigma(v_i), \frac{n+1}{2}) \text{ where } n \text{ is odd.} \end{cases}$

Proof: Let $G^S = (V, E, \sigma, \psi)$ be a given S-valued graph. Consider the cycle on n vertices, C_n^S .

Let $\{v_1, \sigma(v_1)\} \in V_S$ be any vertex in the cycle C_n^S with $N_S(v_1) = \{(v_2, \sigma(v_2)), (v_n, \sigma(v_n))\}$.

This implies that $\{(v_1, \sigma(v_1))\}$ dominates both $(v_2, \sigma(v_2))$, and $(v_n, \sigma(v_n))$.

Take $\{v_3, \sigma(v_3)\} \in V_S$ that lies on the cycle C_n^S then $\{v_3, \sigma(v_3)\}$ dominates $(v_2, \sigma(v_2))$ and $(v_4, \sigma(v_4))$.

Continuing in this way, we choose vertices not in $N_S(v_i)$ for any v_i chosen previously. Then

$N_S(v_{n-1}) = \{(v_{n-2}, \sigma(v_{n-2})), (v_n, \sigma(v_n))\}$.

When **n is even**, there will be no vertices remaining and hence we conclude that

$T_D^S = \{(v_1, \sigma(v_1)), (v_3, \sigma(v_3)), \dots, (v_{n-1}, \sigma(v_{n-1}))\}$ is a total weight dominating vertex set showing that $N_S[T_D^S] = \{(v_1, \sigma(v_1)), (v_2, \sigma(v_2)), \dots, (v_n, \sigma(v_n))\}$. Therefore

$\gamma_{T_D^S}^S(G^S) = (\sum \sigma(v_i), \frac{n}{2})$ where n is even.

When **n is odd**, the edge ending with $(v_{n-1}, \sigma(v_{n-1}))$ in C_n^S , will not be covered. Hence we need to add one more vertex which will dominate both v_{n-1} and v_n . Then the cycle will have (n+1) vertices. Hence

$\gamma_{T_D^S}^S(G^S) = (\sum \sigma(v_i), \frac{n+1}{2})$ where n is odd.

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